

GIORGIO METTA

PhD, Robotics Guru



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ABOUT ME

Date of birth: January 14, 1970

Place of birth: Cagliari, ITALY

CONTACT

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IN A NUTSHELL

330 Scientific Publications

40+ iCub available worldwide

22 European Research Grants

11 Industrial Grants

8 Patents

30+ Graduated PhD students

56: Google Scholar h-index

ON THE WEB

<https://www.facebook.com/giorgio.metta.9>

<https://www.linkedin.com/in/giorgio-metta-9ab2025/>

<https://github.com/robotology>

<http://www.icub.org>

ACADEMIC APPOINTMENTS

- Since 2019 SCIENTIFIC DIRECTOR of the Istituto Italiano di Tecnologia
- 2016-2019 VICE SCIENTIFIC DIRECTOR of the Istituto Italiano di Tecnologia
- 2012-2019 DIRECTOR of the "iCub Facility" at the Istituto Italiano di Tecnologia in Genoa
- 2012-2019 PROFESSOR (20% FTE) of Cognitive Robotics at Plymouth University, UK
- 2012-2016 DEPUTY DIRECTOR of the Istituto Italiano di Tecnologia, delegate to the relations with the external funding agencies
- 2006-2011 SENIOR RESEARCHER at the Istituto Italiano di Tecnologia in Genoa
- 2005-2011 ASSISTANT PROFESSOR (with tenure) at the University of Genoa, Italy

POSTDOCTORAL POSITIONS

- 2003-2004 POSTDOC at the University of Genoa including teaching duties, EU project coordination (FET project ADAPT)
- 2001-2002 POSTDOCTORAL ASSOCIATE, MIT, AI-Lab, Cambridge, USA
- Full time research position at the AI-Lab, in Prof. Rodney Brooks' group

EDUCATION

- 1996-2000 PHD in Computer Science and Electronic Engineering from the University of Genoa
- 1995-1995 RESEARCH FELLOW at University of Leeds, UK
- 1989-1994 MSc DEGREE magna cum laude in Electronic Engineering from the University of Genoa, Italy

RESEARCH

I coordinated the development of the iCub robot for more than a decade making it *de facto* the reference platform for research in embodied AI. Presently, there are more than 40 robots reaching laboratories as far as Japan, China, Singapore, Germany, Spain, UK and the United States. My research activities are in the fields of biologically motivated and humanoid robotics and, specifically, in developing humanoid robots that can adapt and learn from experience.